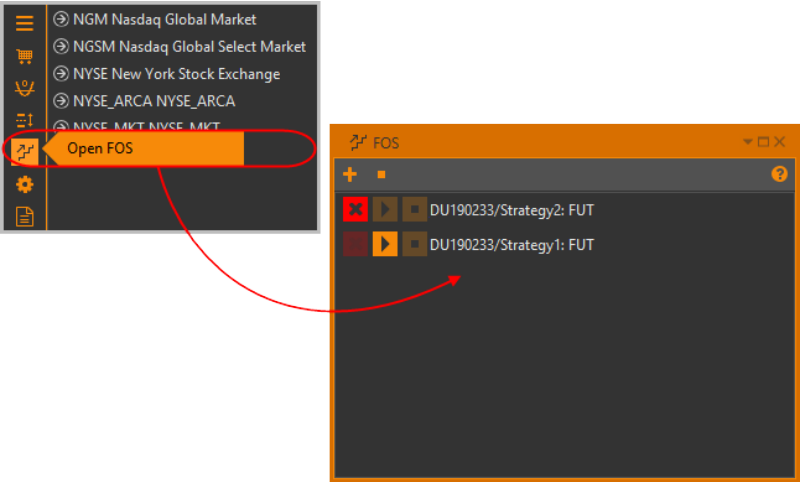
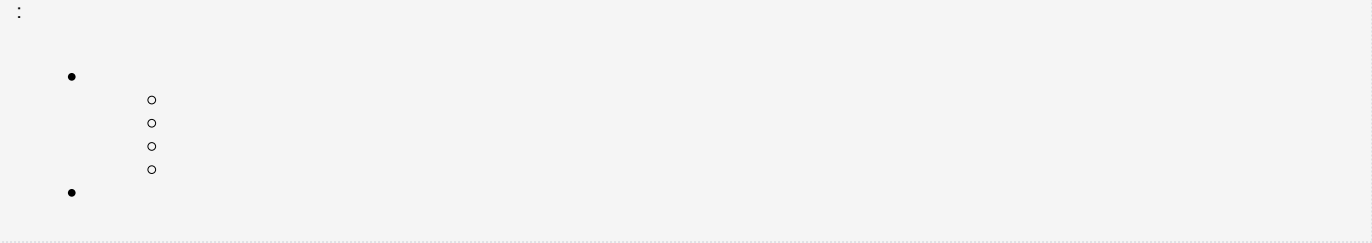


(FOS)

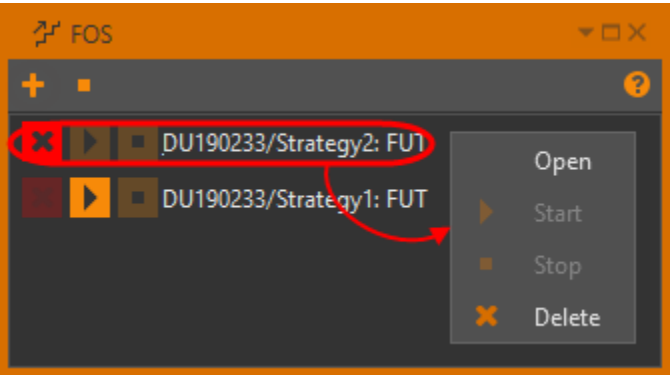
FOS (. 1).



1 – FOS

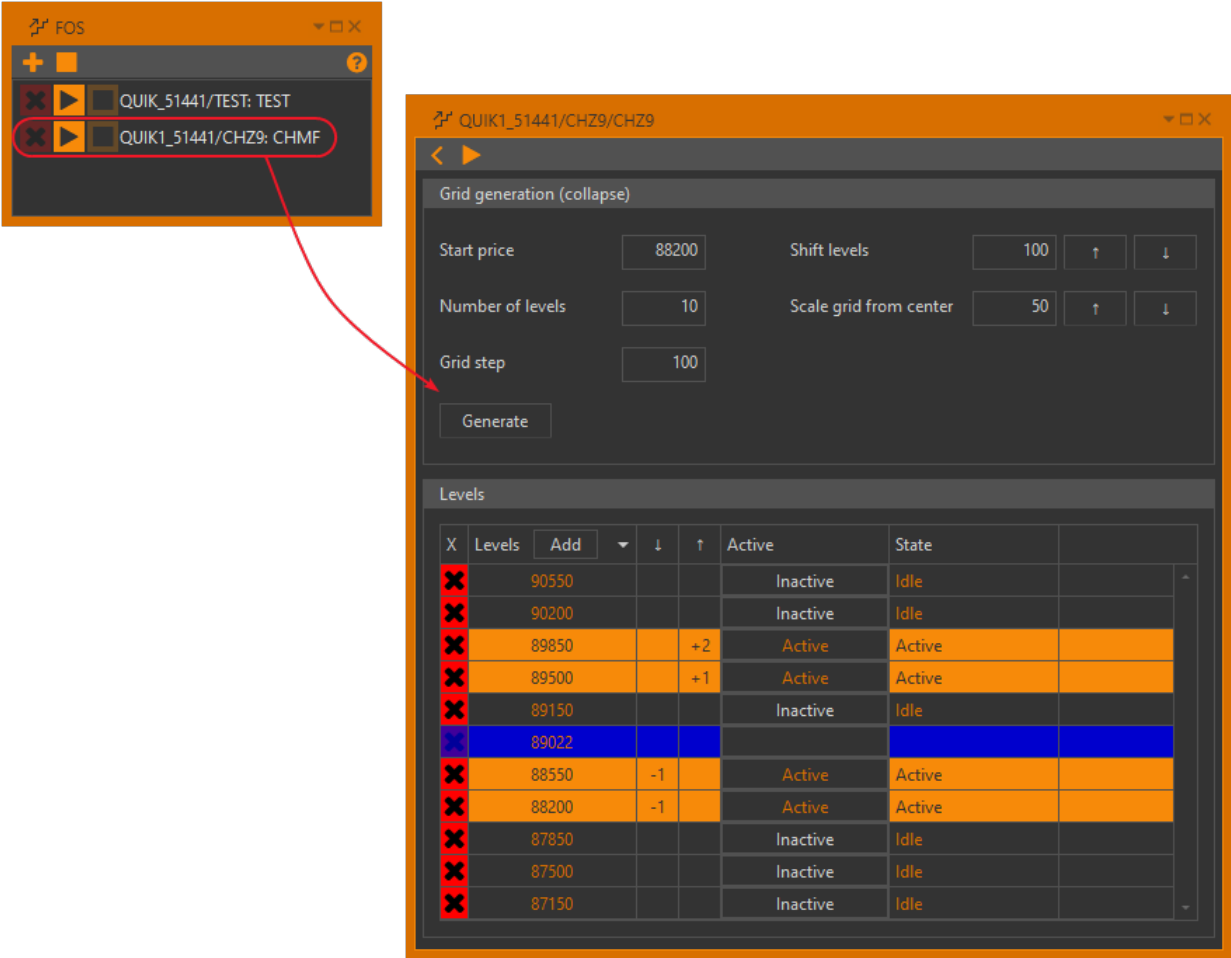


(. 2).



2 –

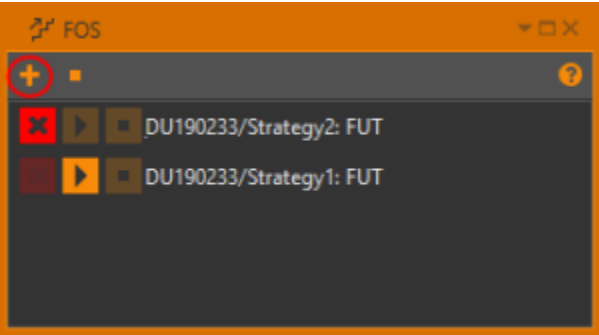
Open (. 2). (. 3).



3 – FOS, Levels. , , .

:

1.  FOS (. 4).



4 – FOS

2. :
• ,
• ,

- ,
- , (. 5).

Add new FOS robot

Name

FOS3

Account

DU190233

Strategy

Strategy1

Instrument

CD

OK

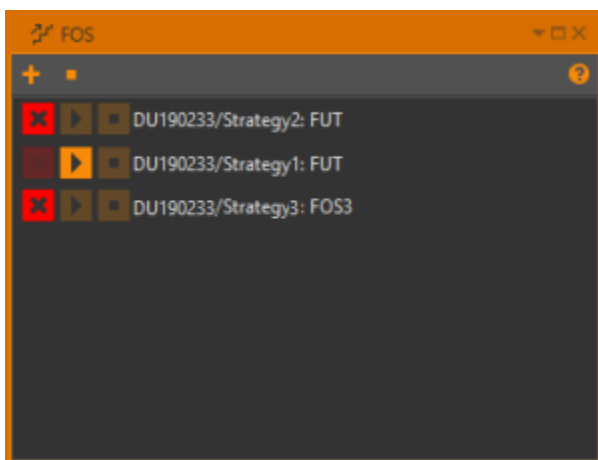
Cancel

5 –



FOS.
actual.

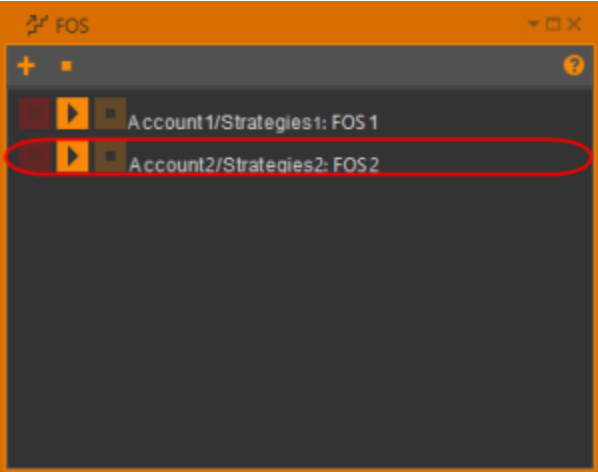
FOS (. 6).



6 –

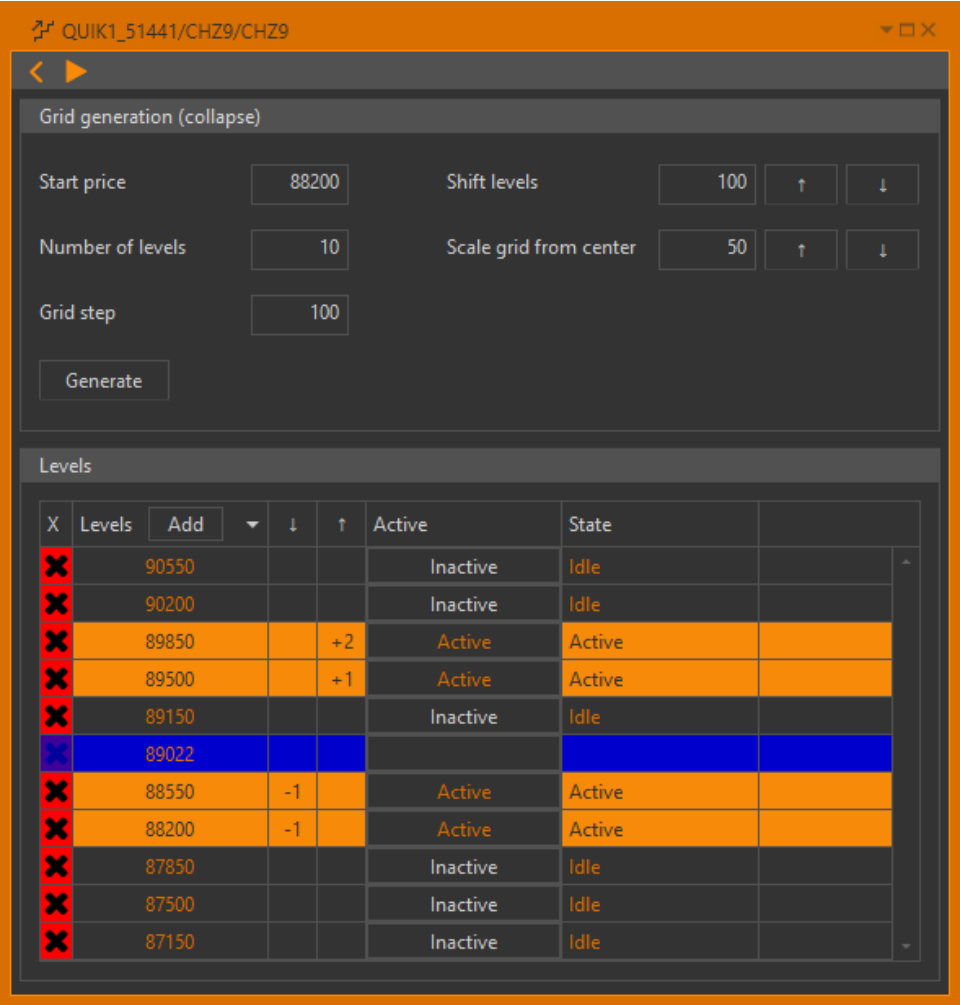
:

1. FOS (. 7);



7 –

2.  FOS (. 8).



8 –

- . Levels **Inactive.** **Active.**
- FOS .



FOS .



FOS.



Grid generation (collapse) (. 9):

- Start price – ();
- Number of levels – ();
- Grid step – , ;
- Shift levels – N ;
- Scale grid from center – N , - .

<

>

Grid generation (collapse)

Start price

88200

Shift levels

100

↑

↓

Number of levels

10

Scale grid from center

5

↑

↓

Grid step

100

Generate

9 –

Grid generation (collapse) , , , Grid generation (expand).

(. 10).

Levels							
X	Levels	Add	▼	↓	↑	Active	State
✖	90550					Inactive	Idle
✖	90200					Inactive	Idle
✖	89850				+2	Active	Active
✖	89500				+1	Active	Active
✖	89150					Inactive	Idle
✖	89022						
✖	88550			-1		Active	Active
✖	88200			-1		Active	Active
✖	87850					Inactive	Idle
✖	87500					Inactive	Idle
✖	87150					Inactive	Idle

10 –

Levels 1.

1 - Levels

X		
Levels , Add	,	Add () : - 1. ().
		: • «1» - «+1» - . • «-1» - . , : 1, 2, 3 .. . Ctrl+Enter.
		: • «1» - «+1» - • «-1» - , : 1, 2, 3 .. . Ctrl+Enter.
Active		: • Inactive - , . • Active - .
State		: • Idle - (). • Active - (). • Stopping - ().

() . FOS .

FOS ().